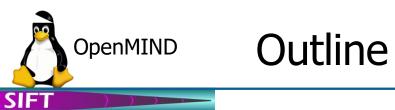


OpenMIND: Planning and Adapting in Domains with Novelty

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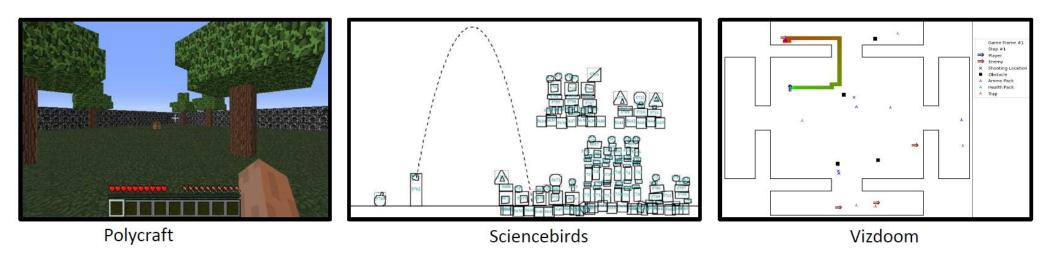


- Background: the DARPA SAIL-ON program.
- What is novelty?
- What is novel in the research?
- Evaluation approach.
- Results so far.
- Lessons.



The SAIL-ON Problem

- Science of Artificial Intelligence and Learning for Open-world Novelty.
- Objective: a (mostly) domain-independent, competent agent that can adapt to novelty in its environment.
- Competent: either pre-trained or engineered to be capable of accomplishing one or more tasks in its expected environment.
 - Not a tabula rasa problem, not pure RL from scratch.
- Our version: a planning and plan-execution agent.
 - New goals are not the novelties... the novelties are in the domain.

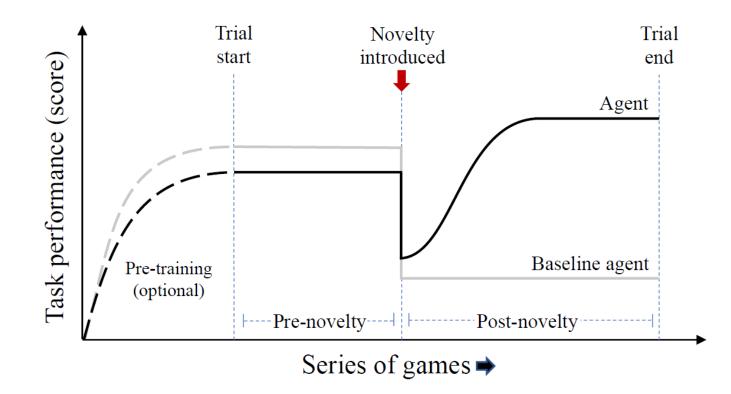




- I know it when I see it, because I haven't seen it before.
- Or, per Pat Langley's AAAI'20 paper: detectable, sudden, persistent changes to the agent's environment.
- Some novelties are opportunities, some are impediments, some are irrelevant.



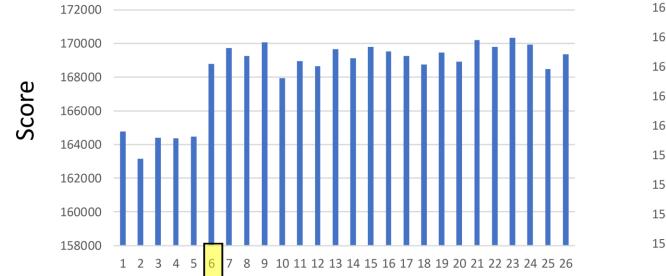
Evaluation Approach



- Multiple "trials", each consisting of a series of "instances" (games).
 - Agent starts each trial fresh, without accumulating learning between trials learning is within a trial.
- In some trials, at some point the Red Button is pushed (without telling the agent) and novelty arrives.
- Agents should report novelty as soon as detected, and adapt as needed to continue performing task.
- Metrics assess detection and performance adaptation.

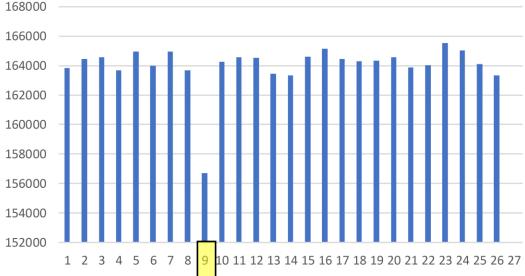


- Axes in Polycraft make it cheaper to break trees into logs.
- But the recipe for making an axe from scratch costs more than the axe can save in a game.
- If you have an axe, use it.
- If you only have an axe recipe, ignore it.



Axe In Inventory



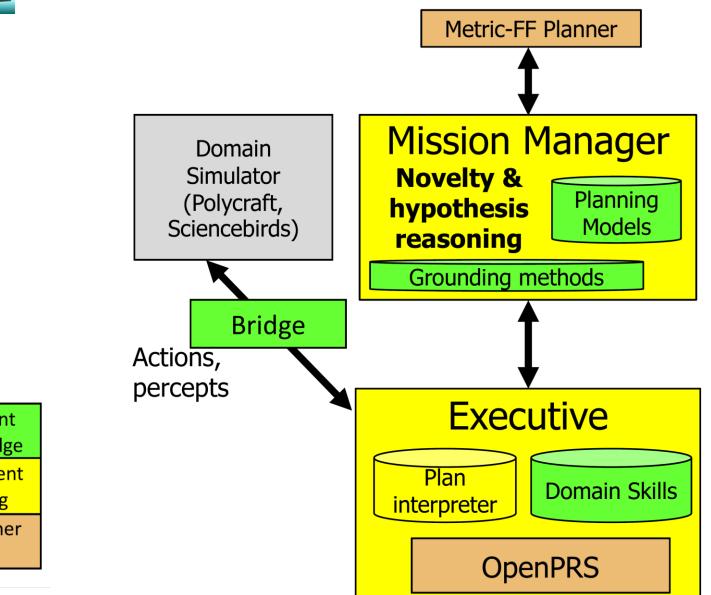


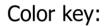


- Not the architecture— a fairly common planning and execution scheme, with meta-control.
- Not the planner– Metric-ff, currently.
- Not the adaptation approach: adapt planning models and goals.
- (1) New domain-independent heuristics for model and goal adaptation.
- (2) Single-blind evaluation on unrevealed novelties (a SAIL-ON program-wide innovation).
 - Simulation developers provide a very small set of example novelties of different types (novel objects, novel other-agents, etc).
 - Evaluation, performed by the sim developers, uses "unrevealed" novelties.



OpenMIND Architecture





Domain-dependent bootstrap knowledge Domain-independent novelty reasoning Open source planner and executive



Unexpected observations

E.g.

- Planner failures.
- Plan execution failures.
- Unrecognized item class detected.
- Unrecognized item feature detected.

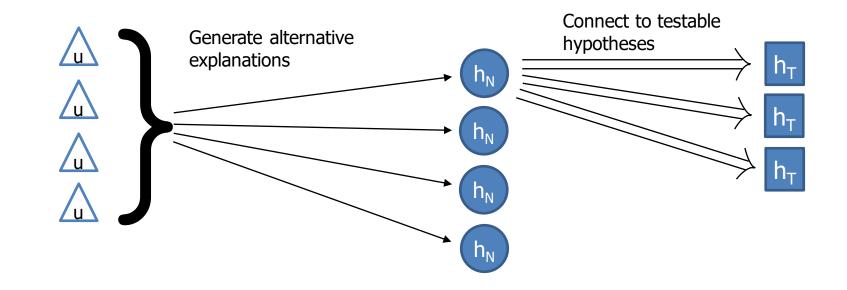
h_N Novelty hypotheses

- Characterize novelty holistically.
- Assumption can produce new operators in domain-independent fashion.

E.g.:

- Perception of features F on items I is transformed by T (level 3).
- Novel class C is a beneficial parameter (tool) for action A (level 1).

- Testable hypotheses
 - Can be validated/rejected by experimentation. E.g.
 - An operator can be executed successfully.
 - One operator will have lower cost than another.
 - An operator will have a particular effect.
 - An operator will make it possible to create a plan, when before it was not possible.



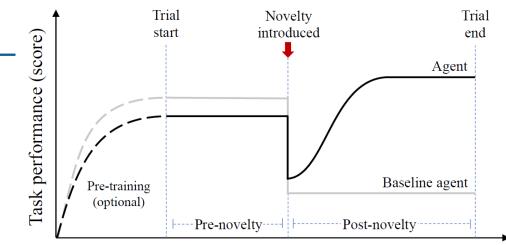


- Depending on type of unexpected observations.
- Preferred operator use specific parameters (e.g., an axe) in certain actions.
 - "When I break blocks with the axe, I get lower action costs".
- Prefix game goal try to achieve an early goal (e.g., make an axe) before pursuing the usual goal.
- Bad arguments avoid using specific parameters in certain actions.
 - "When I try to break block-27, over and over, it doesn't work...so I won't do that anymore".
- Misrepresentation something is wrong in the percepts, try a transform (e.g., recipe rotation).
- Novelty-removal hypotheses: last-resort domain-independent tactic for handling interfering novelty.
 - "When I break fence blocks, I'm able to achieve my original goals".
- Repeat hypothesis handling keep trying them, even if they didn't help the first time.
- Do-anything goals: last-resort domain-independent tactic for handling imperceptible novelty.
 - "I can't see anything novel, and there are no pigs to shoot...but the game isn't over... I'll shoot anything".



SAIL-ON Program-Wide Metrics

CDT = Correctly Detected Trial



Series of games ⇒

Measure	Туре	Definition		
M1: <i>M_{FN}</i>		Mean # of FNs among $CDTs^{\dagger}$		
M2: <i>M</i> % <i>CDT</i>	Distribution Change Detection	% of CDTs (among all Trials)		
M2.1: <i>M</i> _{%<i>FP</i>}	change Detection	% of Trials with at least 1 FP		
M3: <i>M_{NRP}</i>	Performance Task	$rac{lpha_{post}}{eta_{pre}}$		
		Ppre		



- Generally improving results.
- Removing semi-random false-positive detector in Sciencebirds reduced CDT (bad) but also FP% (good).

	FN_CDT		CDT_%		FP_%	
	M12	M18	M12	M18	M12	M18
Polycraft	2.4	0.6	82.0%	88.5%	4.6%	0.0%
Sciencebirds	27.8	23.0	68.3%	27.2%	12.6%	0.6%

	NRP		
	M12	M18	
Polycraft	81.7%	81.0%	
Sciencebirds	84.0%	182.8%	



- Fairly simple, completely domain-independent, and somewhat syntactic modifications to planning operators lead to routinely-effective changes in behavior.
 - This really is a validation of the notion of symbolic planning and the representations it uses
 – the whole idea is to have declarative models support goal-achieving behavior.
- Insight: very general knowledge-poor novelty-handling strategies are feasible and effective, without explanatory hypotheses or models.
- Insight: some stochastic behavior by our agent would mitigate some forms of obstructive novelties, without detection or focused response.
 - E.g., Sciencebirds "awning" instance.



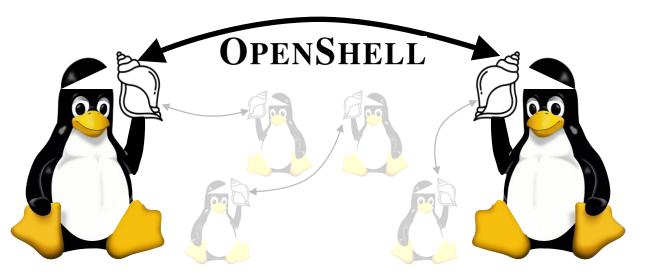
• Simulation Bug or Novelty?



Future Directions

- More structured design of experiments.
- Multi-step validation/refutation: accumulation of evidence.
- Postcondition modification hypotheses (e.g., break-block results in more than one log).
- Operator success/fail probability modeling for change detection.
- Explore/exploit tradeoff: learn from domain?
- Other possible directions: extend qualitative modeling of kinematics.

• Sharing info among lifelong learners.





Questions?